Seat No. : \_\_\_\_\_

# **13E-110**

# May-2015

# M.Sc., Sem.-II

## 409 : Statistics

### (Mathematical Programming)

Time : 3 Hours]

[Max. Marks : 70

Instructions	:	(1)	Attempt all questions.
		(2)	All questions carry equal marks.

1. (a) Describe the revised simplex method for solving a linear programming problem.

OR

Compare the revised simplex method with simplex method and bring out the salient points of differences.

(b) Describe the dual simplex method for solving a linear programming problem.

OR

Explain with suitable examples the basic philosophy behind sensitivity analysis.

(a) Discuss sensitivity analysis with respect to change in the objective function coefficient C<sub>i</sub>.

OR

Explain what is meant by a parametric linear programming problem, pointing out its chief characteristics.

(b) Explain the method of solving a zero-sum two person game as a linear programming problem.

#### OR

Discuss the changes in the components  $a_{ij}$  of the vector  $a_j \in B$  for the given LP problem :

Max.  $Z = c^T x$ , subject to Ax = b,  $x \ge 0$ .

13E-110

**P.T.O.** 

3. (a) Discuss dynamic programming with suitable examples.

#### OR

Explain branch and bound method in integer programming.

(b) Explain fractional programming with suitable examples.

### OR

What is all integer linear programming ? Explain Gomory's all integer cutting plane method.

4. (a) Explain modified simplex method of goal programming.

### OR

What is goal programming ? Why are all goal programming problems minimization problems ? Why does altering the goal priorities result in a different solution to a problem ? Explain.

(b) Explain graphical solution method for goal programming.

#### OR

Explain the differences/similarities between linear programming and goal programming.

- 5. Answer the following :
  - If either the primal or the dual LP problem has an unbounded objective function value, then the other problem has no feasible solution.
    - (a) True (b) False
  - (2) Addition of an additional constraint in the existing constraints will cause a
    - (a) change in objective function coefficients  $c_j$
    - (b) change in coefficients a<sub>ii</sub>
    - (c) both (a) and (b)
    - (d) none of the above

### 13E-110

- (3) A change in the objective function for a non-basic variable can affect
  - (a)  $c_j z_j$  values of all non-basic variables
  - (b)  $c_j z_j$  values of all basic variables
  - (c) only the  $c_j z_j$  value of that variable
  - (d) none of the above
- (4) Game theory models are classified by the
  - (a) number of players
  - (b) sum of all payoffs
  - (c) number of strategies
  - (d) all of the above
- (5) What happens when maximin and minimax values of the game are same ?
  - (a) no solution exists (b) solution is mixed
  - (c) saddle point exists (d) none of the above
- (6) A game is said to be \_\_\_\_\_ if lower and upper values of the game are same as well as zero.
- (7) Define zero-one integer programming.
- (8) The situation of multiple solutions arises with
  - (a) cutting plane method (b) branch and bound method
  - (c) both (a) and (b) (d) none of the above
- (9) The corners of the reduced feasible region of an integer LP problem contains
  - (a) only integer solution (b) optimal integer solution
  - (c) only non-integer solution (d) none of the above
- (10) While applying the cutting-plane method, dual simplex is used to maintain

3

- (a) optimality (b) feasibility
- (c) both (a) and (b) (d) none of the above

13E-110

**P.T.O.** 

(11) The GP approach attempts to achieve each objective

(a)	sequentially	(b)	simultaneously
-----	--------------	-----	----------------

(c) both (a) and (b) (d) none of the above

(12) In optimal simplex table of GP problem, two or more  $c_j - z_j$  rows indicate

- (a) unequal priority goals (b) equal priority goals
- (c) priority goals (d) unattainable goals
- (13) Deviational variables in GP model must satisfy the following conditions :
  - (a)  $d_i^- \times d_i^+ = 0$  (b)  $d_i^+ d_i^- = 0$
  - (c)  $d_i^+ + d_i^- = 0$  (d) none of the above
- (14) Dynamic programming approach optimizes a sequence of interrelated decision over a period of time.

(a)	True	(b)	False
-----	------	-----	-------

13E-110